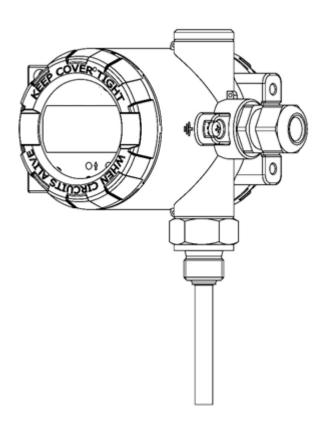


# **USER'S MANUAL**

TEMPERATURE TRANSMITTER

# LI-24ALW

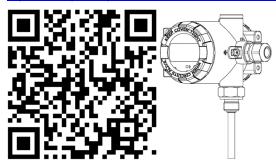


#### PRODUCT CODE – see → 5.2. Transmitter identification.

The QR code or ID number identifies the transmitter and provides quick access to the following documentation on the manufacturer's website: user's manual, explosion-proof device user manual, declarations of conformity and copies of certificates.

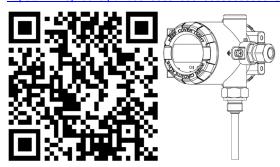
#### LI-24ALW

ID:0028 0001 0001 0000 0000 0000 0001 28 https://www.aplisens.pl/ID/002800010001000000000000000128/en.php



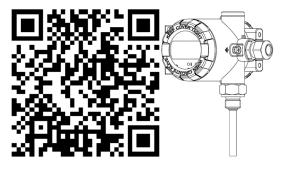
# LI-24ALW (Exi)

ID:0028 0002 0001 0000 0000 0001 45 https://www.aplisens.pl/ID/00280002000100000000001000145/en.php



# LI-24ALW (Exd)

ID:0028 0003 0001 0000 0000 0002 0001 62 https://www.aplisens.pl/ID/002800030001000000000002000162/en.php



Symbols used

Symbol Description					
$\triangle$	Warning to proceed strictly in accordance with the information contained in the documentation in order to ensure the safety and full functionality of the device.				
i	Information particularly useful during installation and operation of the device.				
⟨£x⟩	Information particularly useful during installation and operation of an Ex type device.				
Z	Information on disposal of used equipment.				

#### **BASIC REQUIREMENTS AND SAFE USE**

The manufacturer will not be liable for damage resulting from incorrect installation, failure to maintain a suitable technical condition of the device or use of the device other than for its intended purpose.



Installation should be carried out by qualified staff having the required authorizations to install electrical and I&C equipment. The installer is responsible for performing the installation in accordance with manual as well as with the electromagnetic compatibility and safety regulations and standards applicable to the type of installation.

All safety and protection requirements must be observed during installation, operation and inspections.

If a malfunction occurs, the device should be disconnected and handed over to the manufacturer for repair.



In order to minimize the risk of malfunction and associated risks to staff, the device is not to be installed or used in particularly unfavourable conditions, where the following hazards occur:

- possible mechanical impacts, excessive shocks and vibration;
- excessive temperature fluctuation;
- water vapour condensation, dusting, icing.

Changes made to the manufacturing of products may be introduced before the paper version of the manual is updated. The up-to-date manuals are available on the manufacturer's website: <a href="https://www.aplisens.com">www.aplisens.com</a>.



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#### 1. INTRODUCTION

## 1.1. Purpose of the document

The subject of manual are smart temperature transmitters **LI-24ALW**, designed to work with a distance or direct sensor. The manual applies to the following versions: standard, intrinsically safe Exi and flame-proof Exd.

The manual contains data, tips and general recommendations for safe installation and operation of the transmitters, as well as troubleshooting in case of possible failure.

The manual does not cover explosion protection issues.



The use of the equipment in hazardous zones without appropriate approvals is forbidden.

It is mandatory to read EN.IX.LI.24.ALW Explosion-proof Device User Manual, containing important information related to the installation of intrinsically safe and flameproof versions of the transmitters.

# 1.2. Registered trademarks

HART® is a registered trademark of FieldComm Group. Windows® is a registered trademark of Microsoft Corporation. Google Play® is a service registered and managed by Google® Inc.

#### 2. SAFETY

- The installation and start-up of the device and any activities related to operation shall be carried out after thorough examination of the contents of user's manual and the instructions related thereto.
- Installation and maintenance should be carried out by qualified staff having the required authorizations to install electrical and measuring devices.
- The device shall be used according to its intended purpose in line with the permissible parameters specified on the nameplate (→ 5.2. Transmitter identification).



- The protection elements used by the manufacturer to ensure transmitter safety may be less effective if the device is operated in a manner not consistent with its intended purpose.
- Before installing or disassembling the device, it is absolutely necessary to disconnect it from the power source.
- No repairs or alterations to the transmitter electronic system are permitted. Assessment of damages and possible repair may only be performed by the manufacturer or authorized representative.
- Do not use instruments if damaged. In case of malfunction, the device must be put out of operation.



#### 3. TRANSPORT AND STORAGE

## 3.1. Delivery check

After receiving the delivery of the equipment, it is necessary to:

- make sure that the packaging and its contents were not damaged during transport;
- check the completeness and correctness of the received order, make sure no parts are missing.

## 3.2. Transport

Transport of transmitters shall be carried out with the use of covered means of transport, in original packages. The packaging shall be protected against movement and direct impact of atmospheric factors.

#### 3.3. Storage

Transmitters shall be stored in a factory packaging, in an indoor room without vapours and aggressive substances, protected against mechanical impact, at an air temperature and relative humidity not exceeding the permissible ambient parameters in accordance with data sheet.

## 4. GUARANTEE

General terms and conditions of guarantee are available on the manufacturer's website: <a href="https://www.aplisens.com/ogolne\_warunki\_gwarancji">www.aplisens.com/ogolne\_warunki\_gwarancji</a>



The guarantee shall be repealed if the device is used against its intended use, failure to comply with user's manual or interference with the structure of the device.



#### 5. IDENTIFICATION

# 5.1. Manufacturer's address

APLISENS S.A. 03-192 Warsaw Morelowa 7 St Poland

#### 5.2. Transmitter identification

Depending on the version of the transmitter, the nameplates may differ in the amount of information and parameters.

 Table 1. Symbols occurring on the transmitter nameplate

PLISENS® APLISENS S.A.	Logo and name of manufacturer		
CE	CE mark		
<b>C €</b> 1453	CE mark with the number of notified body		
5000 2000	QR code		
TYPE:	Transmitter type		
ID	Transmitter model ID		
<b>──</b>	Type of measurement input		
<b>→</b> U	Supply voltage values		
→ Tamb	Permissible range of ambient temperature		
<u></u> →• I	Output signal		
El. connection:	Type of electrical connection		
Ser No.	Transmitter serial number		
Year of production	Year of production		
IP	IP range value		
//lower part of the nameplate//	Special version		
	Note about the read the manual		
Aplisens S.A. ul. Morelowa 7, 03-192 Warszawa	Manufacturer address		

#### 5.3. CE mark, declaration of conformity

The device has been designed to meet the highest safety requirements, it has been tested and has left the factory in a condition that is safe for operation. The device complies with the applicable standards and regulations listed in the EU Declaration of Conformity and has CE marking on nameplate.



#### 6. CONSTRUCTION

#### 6.1. Construction

The basic transmitter assemblies are the housing and the electronic assembly converting the signal from the measuring sensor into a unified output signal. The electronics main board with display is placed in a polycarbonate cover. This assembly is located in a larger-one housing chamber, where it can be rotated ±180° with 90° step. This allows you to change the position of the display. In the second chamber there is a connecting plate, also protected by a polycarbonate cover, with connection terminals.

#### 6.2. Measurement principle

The measuring sensor, i.e. thermometric resistor or measuring junction of the thermocouple, sends signal corresponding to the measured medium temperature to the input of the analog-to-digital converter, where it is converted into digital form. The digital signal is sent via the optoelectronic galvanic barrier to the main board. Microcontroller of the main board reads the measured values and uses the incorporated algorithms to calculate the exact temperature value. The resulting value is displayed on the integrated LCD display which can be configured according to the user's needs. Digital value of the measured temperature is converted to analogue 4 ... 20 [mA] signal. The built-in modem BELL 202 and the implemented communication stack, HART rev 5.1, enable communication with the transmitter via converter connected to a PC with appropriate software or via communicator.

The electric connection of the transmitter is provided with an output interference filter and overvoltage protection components. LI-24ALW transmitter monitors its hardware resources and calculation accuracy. In case of a failure, the transmitter specifies an error code on the LCD display and generates alarm current in the current loop.

Measuring signal from the sensor is isolated galvanically from the current line. As a result the transmitter is less susceptible to interference and provides better safety of work in intrinsically safe applications.

#### 7. INSTALLATION

#### 7.1. General recommendations

Temperature transmitter LI-24ALW can be mounted in any position.

The housing of the transmitter should be protected against hot air streams by appropriate location of the transmitter or by installing thermal screens so that the transmitter does not heat up to a temperature higher than the permissible one.

The transmitter housing allows for wall and pipe mounting. For this purpose, use the AL handle by Aplisens S.A.



#### 8. ELECTRICAL CONNECTION



All connection and installation operations must be performed with disconnected supply voltage and other external voltages, if used.



Failure to provide proper connection of the transmitter may result in danger. Risk of electric shock and/or ignition in potentially explosive atmospheres.

#### 8.1. Cable connection to transmitter terminals

In order to perform correct connection of the cables, the following steps shall be performed:

- disconnect power supply;
- unscrew the rear cover of the transmitter body in order to gain access to the terminals of power supply and measurement and the internal ground terminal;
- pull the cable through the cable gland;
- power supply and signal cables of the 4 ... 20 mA current loop should be properly connected to the "+", "-" terminals;
- connect the transmitter in accordance with figures below and section → 8.1.1. Options for connecting sensors, potentiometers and voltage sources to the transmitter, paying attention to the correct tightening of the screws fixing the conductor core to the terminal;
- depending on the type of installation grounding adopted, connect the shield of the cable to the earth screw terminal of the body;
- tighten the rear cover of the transmitter body;
- leaving a slight slack in the cable inside the body, tighten the glands nut so that the gland seal tightens on the cable.

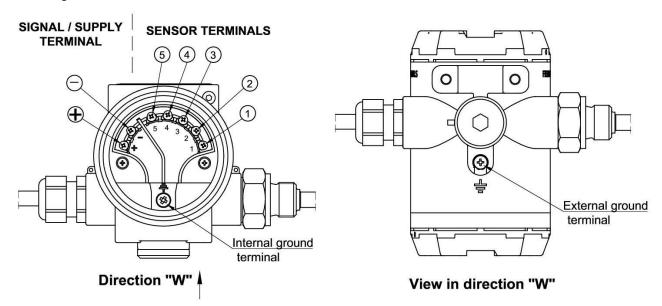


Figure 1. Marking of the LI-24ALW terminals



# 8.1.1. Options for connecting sensors, potentiometers and voltage sources to the transmitter

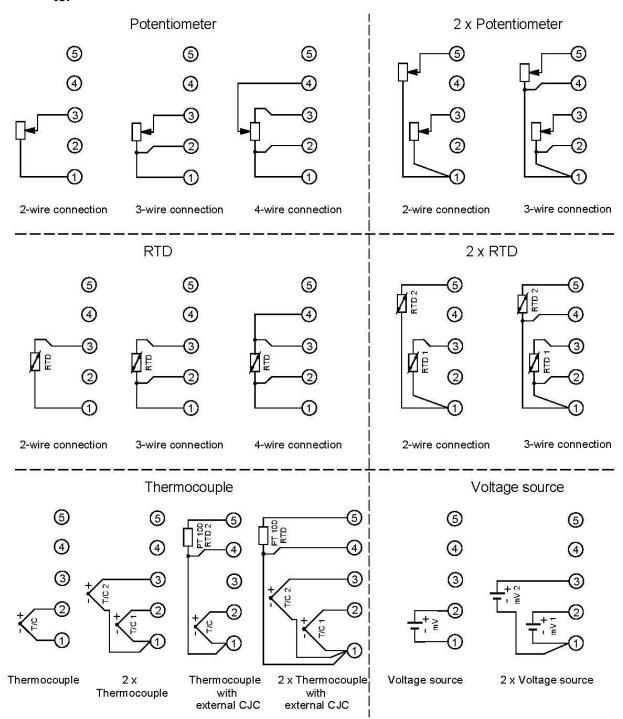


Figure 2. Methods of connecting sensors, potentiometers and voltage sources



#### 8.1.2. Connection of transmitters with the option of using HART communication

The method of connecting a modem to transmitter for HART communication is shown in the figures below.



In order to communicate using connected HART modem to the "+" and "-" of transmitter terminals, make sure that the  $R_{Lmax}$  resistance viewed from the side of transmitter terminals towards power source is in the range of 240  $\Omega \le R_{Lmax} \le 1100 \Omega$ .

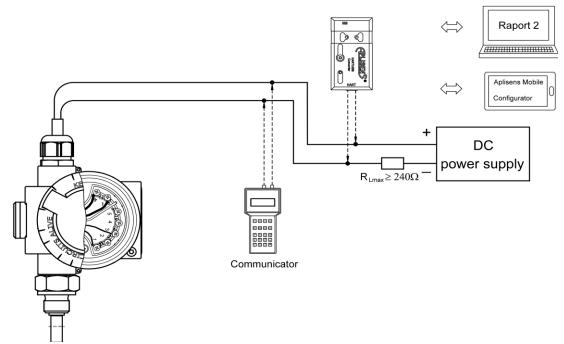


Figure 3. Electrical connection 4 ... 20 mA of HART to transmitters in standard version

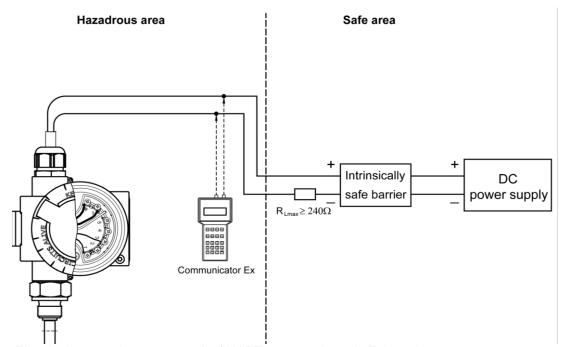


Figure 4. Electrical connection 4 ... 20 mA of HART to transmitters in Exi version



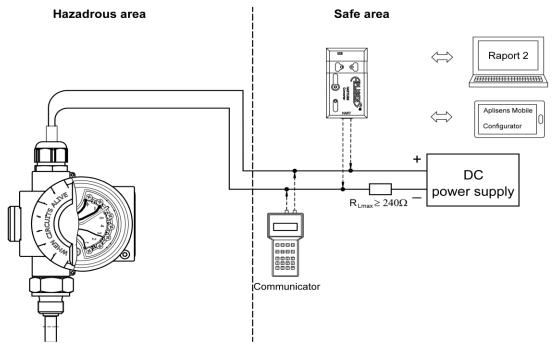


Figure 5. Electrical connection 4 ... 20 mA of HART to transmitters in Exd version



It is mandatory to read EN.IX.LI.24.ALW Explosion-proof Device User Manual, containing important information related to the installation of transmitters in intrinsically safe and flameproof versions.

The HART/USB converter by Aplisens S.A. may also be operated using **Aplisens Mobile Configurator** installed on smartphones with Android system and connected using wireless communication. The software is available on Google Play<sup>®</sup>:

https://play.google.com/store/apps/details?id=com.aplisens.mobile.amc.

#### 8.2. Transmitter power supply

# 8.2.1. Transmitter supply voltage



Power cables may be live.

In case of incorrect connection there is a risk of electric shock and/or explosion.



Installation of the transmitter in explosion-risk atmospheres must comply with the requirements of relevant instructions and national standards and regulations.

Table 2. Permissible transmitter supply voltages

Version	Minimum supply voltage	Maximum supply voltage
Standard	13,5 V DC	55 V DC
	16,5* V DC	55 V DC
Exi	13,5 V DC	30 V DC
	16,5* V DC	30 V DC
Exd	13,5 V DC	45 V DC
	16,5* V DC	45 V DC

<sup>\*</sup> Minimum supply voltage with backlight on. The backlight can only be switched on at the production stage of the transmitter.



#### 8.2.2. Specifications of electrical switching terminals

The internal electrical terminals accept wires with a cross section of 0,5 to 1,75 mm<sup>2</sup>. Internal and external electrical terminal of the body ground accepts wires with a cross-section from 0,5 to 4 mm<sup>2</sup>.

Possible cables to be used:

- unshielded when using the analogue signal only;
- shielded, approved for the HART communication;
- shielded on the sensor(s) side for a cable length greater than 30 m or over-normative radio interference.

#### 8.2.3. Resistance load in power supply line

The power line resistance, power source resistance and other additional serial resistances increase the voltage drops between the power source and the transmitter terminals. The maximum transmitter current under normal operation conditions is defined as I\_max = 21,600 mA (the maximum possible current value issued by the user is 23,000 mA).

The maximum resistance value in the power circuit (along with the power cables resistances) is defined by the formula:

$$R_{Lmax} \le \frac{\left(U_{sup} - U_{min}\right)[V]}{0.0235[A]}$$

where:

 $R_{Lmax}$  – maximum power line resistance [ $\Omega$ ],

U<sub>sup</sub> – voltage at the supply terminals of 4 ... 20 mA current loop [V],

U<sub>min</sub> – minimum supply voltage [V] (→ Table 2. Permissible transmitter supply voltages).

#### 8.2.4. Shielding, equipotential bonding

Optimal protection against interference is provided by the earthing of the screen on both sides. In case of electrical potential difference between earthing points of devices which may result in the flow of equipotential currents, the screen shall be earthed on one side.

# 8.3. Final inspection of cabling

After completing the electrical installation of the transmitter, it is necessary to check the following:

- Does the supply voltage measured at the transmitter terminals at maximum set current match the range of supply voltage specified on the transmitter nameplate?
- Is the transmitter connected according to the information given in section → 8.1. Cable connection to transmitter terminals?
- Are all the screws tightened?
- Are the transmitter covers tightened?
- Is the cable gland tightened?



#### 9. START-UP

Upon request the customer receives a transmitter configured according to the setpoints specified in the order. The current base range and the basic unit of the transmitter can be read out from the device via the HART communication.

#### 9.1. Alarms

The alarms signal hardware faults, calculation errors or exceeding the permissible operating ranges of the transmitter. Internal hardware faults include e.g. RAM and FLASH memory failures, damage to the internal oscillator, opto-isolation interface, ADC measurement converter, internal HART modem. External malfunctions are related to damage or improper connection of measurement sensors to the transmitter. Exceeding the permissible operating ranges is related to transmitter operating temperature ranges. The errors are manifested by the transmitter issuing an alarm current in the line and signalling an error code on the display. The alarm current values can be set using the program Raport 2 or by ordering an appropriate alarm configuration in the transmitter from the supplier.



Temperature transmitters LI-24ALW manufactured by Aplisens S.A. meet the alarm requirements Namur NE 89 and Namur NE 43.

**Table 3.** Type and level of alarms

Type of alarm	Value of the alarm current
NORMAL LOW	3,75 mA
NORMAL HIGH	21,6 mA
NAMUR LOW	3,6 mA
NAMUR HIGH	21,0 mA

	Type of alarm	Value of the alarm current
CUSTOM (user's alarm current value)		Alarm current value in the range from 3,6 mA to 23 mA.
	LAST VALUE (no analogue output update)	The value of the alarm current shall be equal to the value of the current at the moment preceding the triggering event.

# 9.2. Configuration of the operating mode

Before starting the work with the transmitter, the following parameters must be configured:

- basic unit of the transmitter process variable;
- measurement input type (voltage/resistance);
- processing characteristics of measurement sensor (selection of sensor linearization characteristics);
- measurement sensitivity range (100 mV / 1000 mV or 400  $\Omega$  / 2000  $\Omega$ );
- type of sensor connections, number of terminals, CJC configuration (internal, external or none);
- type of the mathematical function processing the signal from two sensors (2x RTD 2-wire connection, 2x RTD 3-wire connection, 2x thermocouple, 2x thermocouple with external CJC (see
   Figure 2. Methods of connecting sensors, potentiometers and voltage sources)):
  - difference of measurements from channels: Ch1-Ch2 or Ch2-Ch1;
  - measurement average: 0.5 · (Ch1+Ch2);
  - measurement average with redundancy: 0,5 · (Ch1+Ch2) or Ch2 or Ch1, when one of the sensors is damaged. Redundancy corresponds to the following variants of the sensors connection: 2x RTD 2-wire connection, 2x RTD 3-wire connection, 2x thermocouple, 2x thermocouple with external CJC (alarm deactivation is required);
  - minimum value of the two measurements: min (Ch1, Ch2);
  - maximum value of the two measurements: max (Ch1, Ch2).



In case of using the configuration with linearization, shorting one of the sensors results in triggering an alarm. This is due to the measurement going beyond the linearization table. In non-linearization configurations with resistance sensors, short circuits are undetectable.



- additional parameters such as offset of measuring channels or external compensation of sensor lead resistance;
- start point of the set range (LRV) in the basic unit;
- end point of the set range (URV) in the basic unit;
- damping time constant;
- analogue output processing characteristic mode;
- transmitter tag (TAG);
- setting the password for changing settings;
- setting the write lock after performing the configuration actions.

# 9.3. Metrological parameters, types of sensors, measuring ranges and errors

- User's processing characteristics.
- Input impedance, thermocouple or voltage input:  $> 10 \text{ M}\Omega$ .
- Additional error due to supply voltage changes: ±0,002 %/V.
- Temperature impact compensation: 50-point at operating temperature range, segmental with linear approximation between points.
- Output updates time (calculation cycle): 0,74 ÷ 1,8 s.
- Additional electronic damping: 0 ÷ 30 s.

 Table 4. Metrological parameters of RTD sensors

RTD sensor connected with 2, 3 or 4 wires							
Input – RTD	Input – RTD						
Thermal resistance sens	sors:		2, 3 or 4 w	rires connection	on		
Sensor current:			~420 µA				
Maximum wires resistar	nce:		25 Ω				
Sensor type	Standard	Basic range	Min. range span	Processing error Δ <b>p</b>	Temperature processing error Δ <b>tp</b>	Analogue output error	
		[°C]	[°C]	[K]	[K/K]	[%]	
1	2	3	4	5	6	7	
Pt10 (α=0,003850)		-200÷850	10	±0,8	±0,035	, ,	
Pt50 (α=0,003850)	PN-EN 60751+A2,	-200÷850	10	±0,2	±0,0070		
Pt100 (α=0,003850)	IEC751, DIN43760,	-200÷850	10	±0,07	±0,0035		
Pt200 (α=0.003850)	JISC 1604-97.	-200÷850	10	±0.2	±0.0020		
Pt500 (α=0,003850)	BS 1904	-200÷850	10	±0,05	±0,0007		
Pt1000 (α=0,003850)		-200÷266	10	±0,03	±0,0003		
Pt98 (α=0,003923)	SAMA RC-4-1966	-200÷650	10	±0,07	±0,0035		
Ni100 (W100=1,617)	DN 00/M 50050	-60÷180	10	±0,07	±0,0030		
Cu100 (W100=1,426)	PN-83/M-53952	-50÷180	10	±0,07	±0,0030		
Pt10 (α=0,003916)		-200÷630	10	±0,8	±0,035	Analogue output error is 0,05% FSO (Full Scale	
Pt50 (α=0,003916)	JIS C1604-81	-200÷630	10	±0,2	±0,0070	Output) over the operating	
Pt100 (α=0,003916)		-200÷630	10	±0,07	±0,0035	temperature range.	
Pt10 (W100=1,3910)		-200÷1100	10	±0,8	±0,035	tomporature ranger	
Pt50 (W100=1,3910)		-200÷1100	10	±0,2	±0,0070		
Pt100 (W100=1,3910)		-200÷1100	10	±0,07	±0,0035		
Pt500 (W100=1,3910)	GOST	-200÷900	10	±0,05	±0,00070		
Cu50 (W100=1,426)	6651-94	-50÷200	10	±0,2	±0,0070		
Cu100 (W100=1,426)	000101	-50÷200	10	±0,07	±0,0030		
Cu50 (W100=1,428)		-185÷200	10	±0,2	±0,0070		
Cu100 (W100=1,428)		-185÷200	10	±0,07	±0,0030		
Ni100 (W100=1,617)							
			sistor, potentio			, 	
		[Ω]	[Ω]	[mΩ]	[mΩ/K]		
Measuring range 1		0 400	10	±30	±2	As above	
Measuring range 2		0 2000	10	±120	±2	7	
1	2	3	4	5	6	7	



 Table 5. Metrological parameters of thermocouples

Thermocouples							
Input – Thermocouples							
Input impedance:		> 10	ΜΩ				
Maximum wires resista	ance:		Ω (wires + then				
Cold junctions comper	nsation:	inter	nal sensor, exte	ernal sensor Pt	100,		
		temp	perature consta	nt of the cold ju	ınctions		
Sensor type	Standard	Basic range	Min. range span	Processing error Δ <b>p</b>	Temperature processing error Δ <b>tp</b>	Analogue output error	
		[°C]	[°C]	[K]	[K/K]	[%]	
1	2	3	4	5	6	7	
B (Pt30Rh-Pt6Rh)	DN EN 00754 - A0	500÷1820	50	±0,55	< ±0,001		
E (Ni10Cr-Cu45Ni)	PN-EN 60751+A2,	-150÷1000	50	±0,15	< ±0,001		
J (Fe-Cu45Ni)	IEC584,	-210÷1200	50	±0,20	< ±0,001		
K (Ni10Cr-Ni5)	NIST MN175, DIN43710, BS4937,	-150÷1372	50	±0,30	< ±0,001	Analogue output error is	
N (Ni14CrSi-NISi)	ANSI MC96.1,	-150÷1300	50	±0,25	< ±0,001	0,05% FSO (Full Scale	
R (Pt13Rh-Pt)	JIS C1602,	50÷1768	50	±0,35	< ±0,001	Output) over the operating	
S (Pt10Rh-Pt)	NF C42-321	50÷1768	50	±0,40	< ±0,001	temperature range	
T (Cu-Cu45Ni)	141 042 021	-150÷400	50	±0,15	< ±0,001		
TC Type L	GOST P 8.585-2001	-200÷800	50	±0,20	< ±0,001		
Internal CJC sensor	-	-40÷80	-	±[0,35+0,007 (T-273)]	< ±0,009		
	Voltage						
		[mV]	[mV]	[µV]	[µV/K]		
Measuring range 1		-10 100	10	±6	$< \pm 0.06$	As above	
Measuring range 2		-100 1000	10	±50	$< \pm 0.5$		

$$\Delta G[K] = \Delta p[K] + \Delta t p \left[ \frac{K}{K} \right] \cdot TO[K] + TN[K] \cdot \frac{0,05[\%]}{100[\%]}$$

$$\Delta G[\%] = \frac{\Delta P[K] \cdot 100[\%]}{TN[K]} + \frac{\Delta t p \left[ \frac{K}{K} \right] \cdot TO[K] \cdot 100[\%]}{TN[K]} + 0,05[\%]$$

 $\Delta G$  – limiting error [K] or [%],

TN [K] – span of the measured temperature set range, algebraical difference between the upper and lower limit of the set range,

TO [K] – span of the transmitter ambient temperature range, algebraical difference between the upper and lower ambient temperatures (accepted as the boundary operating temperatures).



Table 6 Types of m

Table 6. Types of measurements, linearization and mathematic	al operations
Voltage measurements, TC type sensors	
Voltage measurement range: 0 100 mV or 0 1000 r	nV
Linearization type / base range	Sensor type and CJC configurations
Linear / 0 100 mV or 0 1000 mV	1 x TC (voltage measurement)
Customised multi-section linear, 21 points / 0 100 mV or 0 1000 mV	2 x TC (voltage measurements)
Type B (IEC 584) / 250 1820°C	1 x TC (without CJC)
Type E (IEC 584) / -200 1000°C	1 x TC (internal CJC – PT100)
Type J (IEC 584) / -210 1200°C	1 x TC (external CJC – PT100, 3-wire)
Type K (IEC 584) / -200 1372°C	2 x TC (without CJC)
Type N (IEC 584) / -200 1300°C	2 x TC (internal CJC – PT100)
Type R (IEC 584) / -20 1768,1°C	2 x TC (external CJC – PT100, 3-wire)
Type S (IEC 584) / -30 1768,1°C	
Type T (IEC 584) / -200 400°C	
Type L (GOST P 8.585-2001) / -200 800°C	
Resistance measurements, RTD type sensors	
Resistance measurement range: 0 400 Ω or 0 2000	Ω
Linearization type/base range	Sensor type configurations
Linear / 0 400 $\Omega$ or 0 2000 $\Omega$	1 x RTD 2 x Wire
Custom multi-section linear, 21 points / 0 400 Ω or 0 2000 Ω	1 x RTD 3 x Wire
PT10 α=0,003850 (IEC 751) / -200 850°C	1 x RTD 4 x Wire
PT10 α=0,003916 (JIS C 1604-81) / -200 630°C	2 x RTD 2 x Wire
PT10 W100=1,3910 (GOST 6651-94) / -200 1100°C	2 x RTD 3 x Wire
PT50 α=0,003850 (IEC 751) / -200 850°C	
PT50 α=0,003916 (JIS C 1604-81) / -200 630°C	
PT50 W100=1,3910 (GOST 6651-94) / -200 1100°C	
PT100 α=0,003850 (IEC 751) / -200 850°C	
PT100 α=0,003916 (JIS C 1604-81) / -200 630°C	7
PT100 W100=1,3910 (GOST 6651-94) / -200 1100°C	
PT200 α=0,003850 (IEC 751) / -200 850°C	
PT500 α=0,003850 (IEC 751) / -200 850°C	
PT500 W100=1,3910 (GOST 6651-94) / -200 900°C	7
PT1000 α=0,003850 (IEC 751) / -200 266°C	
PT98 α=0,003923 (SAMA RC-4-1966) / -200 650°C	
NI100 W100=1,617 (GOST 6651-94) / -60 180°C	
NI100 W100=1,617 (PN-83/M-53952) / -60 180,5°C	
CU50 W100=1,426 (GOST 6651-94) / -50 200°C	
CU50 W100=1,428 (GOST 6651-94) / -185 200°C	
CU100 W100=1,426 (GOST 6651-94) / -50 200°C	
CU100 W100=1,428 (GOST 6651-94) / -185 200°C	
CU100 W100=1,426 (PN-83/M-53952) / -50 180,5°C	
Mathematical operations to be set for CH1 and CH2 char	nels
PV – first process variable mapped in the process current value of the 4 20	
PV = CH1	
PV = CH1 PV = CH2	
PV = CH1-CH2	
PV = CH2-CH1	
PV = (CH1+CH2)/2	
PV=(CH1+CH2)/2 or CH1 if CH2 fails or CH2 if CH1 fails	
PV = min(CH1, CH2)	

PV = min(CH1,CH2) PV = max(CH1,CH2)



#### 10. OPERATION

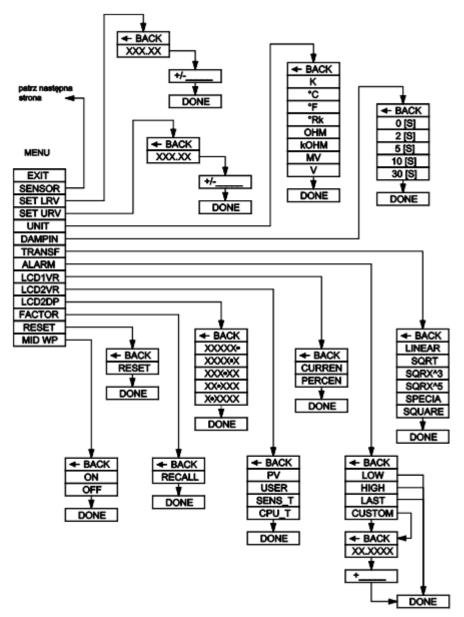
The programmable display is designed to show the values measured during the measurement process. These can be process variables of the measured temperature, current in the current loop or other values converted from the process current variable to the user's units.

#### 10.1. Display configuration

The user can change some transmitter settings, including the display, using the buttons below the display. The buttons can be accessed by unscrewing the display cover. The buttons are marked with symbols:  $[\downarrow]$ ,  $[\uparrow]$  and  $[\bullet]$ .

The buttons  $[\downarrow]$ ,  $[\uparrow]$  are used to move up and down the MENU structure, and the button  $[\bullet]$  confirms and executes the selected option. Pressing and holding any button for about 4 seconds will cause enter to the local setting mode, and the following message "EXIT" appears on the display in the field LCD3. No activity in the MENU area for longer than 2 minutes automatically exits the local setting mode and goes to display process variable. After confirming the selected parameter, the display will confirm the acceptance of the command with a "DONE" message. The " $\leftarrow$  BACK" button allows to move up a level higher in the MENU structure.

The way of navigating in the MENU structure of the local display is shown in the diagram below.





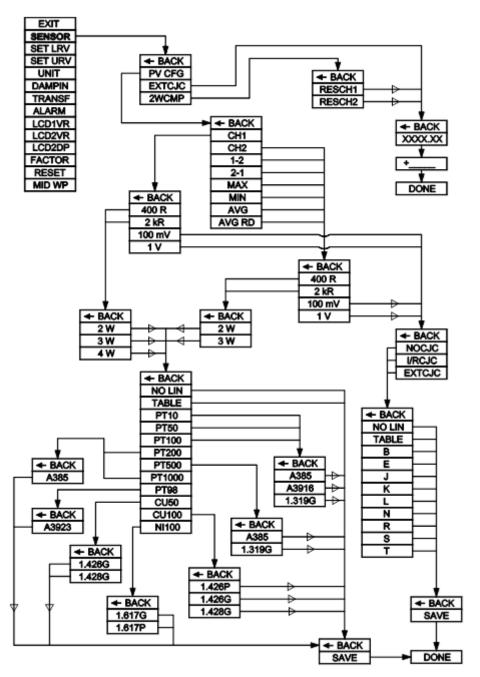


Figure 6. Structure of the local setpoints MENU



Table 7. Structure of the local setpoints MENU

Table 7. Struc	ture of th	ie iocal set	points in⊨nu				
Local MENU	Sub	menu	Description				
EXIT			return from the local MENU to display the process variable				
			setting the start point of the range set LRV / Setting the end point of the range set URV				
SET LRV /	XX	X.XX	the current LRV/URV value is displayed				
SET URV	+/		select and confirm the sign of the parameter to be entered; enter digit by digit, 5-digit number with or without a dot; after confirming the last digit of the parameter, the transmitter will confirm acceptance of the command with "DONE" or will report an error number; the parameter is entered in "UNIT" units				
UNIT			setting of temperature units				
DAMPIN			setting of the damping time constant of the process variable				
			setting the linearization type of current processing characteristics				
		IEAR	linear characteristics				
		QRT	square root function				
TRANSF		RX^3	square root function of x <sup>3</sup>				
		RX^5	square root function of x <sup>5</sup>				
		ECIA	output linearization using user board				
	SQ	UARE	square function				
			setting the transmitter alarm current value				
		OW	low alarm current				
ALARM		IGH	high alarm current				
		<u>AST</u>	last value				
	CUS	STOM	alarm current value set by user				
			type of process variable displayed on LCD1				
LCD1VR		RREN	the LCD1 displays the current value in the current loop				
	PEI	RCEN	the LCD1 displays the percentage of output setpoint				
		51.7	type of variable displayed on LCD2				
1.000/0	PV USER		the LCD2 displays process variable				
LCD2VR			the LCD2 displays the scaled value in user units				
	SENS_T		the LCD2 displays temperature value of ADC converter				
LCD2DD	CPU_T		the LCD2 displays temperature value of microcontroller position of the decimal dot of the variable displayed on LCD2				
LCD2DP FACTORY			removes user's calibration coefficients; returns to factory settings				
RESET			transmitter metrological parameters reset override				
MID WP			sets the write lock of parameters				
IVIID VVI			configuration of the measuring sensor				
	PV	CFG	configuration of the first process variable				
		TCJC	external cold junctions compensation for thermocouples				
		/CMP	compensation of wire resistance for thermocouple				
		SCH1/	resistance of channel 1 / channel 2 wires				
		SCH2					
		CH1	channel 1				
SENSOR	esse	CH2	channel 2				
	ö >	1-2	measurement difference: CH1 - CH2				
	P P	2-1	measurement difference: CH2 - CH1				
	the	MAX	maximum value of the two measurements: max (CH1, CH2)				
	e of the provariable PV	MIN	minimum value of the two measurements: max (CH1, CH2)				
	ne X	AVG	measurement average: 0,5 · (CH1 + CH2)				
	Value of the process variable PV	AVG	measurement average with redundancy: 0,5 · (CH1+CH2) or CH2 or CH1, when one				
	Ť	RD	of the sensors is damaged				
	400R / 2kR		resistance inputs				
	100mV / 1V		voltage inputs				
SENSOR	2W/3W/4W		connection method of RTD sensor (number of wires)				
	NOCJC / I/RCJC / EXTCJC		compensation cold junctions thermocouple				
			resistance inputs				
			voltage inputs				



#### 10.2. Local MENU, error messages

During the execution of some functions in the local MENU, the error message may be displayed on the LCD2 field. Displaying an error means that the local MENU command was not carried out. Errors in the display or incorrect configuration of the display do not affect the value of the process variable in current loop.

# 10.3. View of local LCD display

Display options can be changed in local MENU using buttons. The display is shown in the figure below.

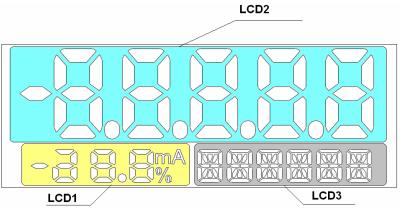


Figure 7. Display information fields

There are three basic fields on the display:

- LCD1 field used to display value of current or setpoint percentage of preset range. Depending
  on the display configuration, it will be displayed the current value in the current line 4 ... 20 mA
  with a resolution of 0,1 mA or setpoint percentage of the preset range with an indication resolution of 1%.
- LCD2 field used to display the measured digital value, the value rescaled by user's unit and error codes. The position of the decimal point can be set in the local MENU or remotely.
- LCD3 information field. During normal operation it is designed for continuous display of the base unit or the user's unit. In the MENU of local setup it displays the setting options. It is also used to display errors related to the execution of commands in the local setup MENU.

#### 10.4. Operating temperature

Standard, Exi version	Exd version
-40 80°C (-40 176°F)	-40 75°C (-40 167°F)

#### 10.5. Remote configuration of setpoints (HART)

The transmitter allows to read and configure parameters via HART communication using 4 ... 20 mA loop as the physical layer for FSK BELL 202 modulation.

#### 10.5.1. Compatible devices

The following devices may be used to communicate with the transmitter:

- HART/USB converter by Aplisens S.A. or converter HART/RS232;
- PC computers equipped with HART modem (e.g. HART/USB converter by Aplisens S.A.) with Windows 7 or Windows 10 operating system with installed the Raport 2 software;
- PC computers equipped with HART modem using software from other companies, accepting DDL and DTM libraries;
- smartphones with Android system, using a converter providing wireless communication (e.g. HART/USB converter by Aplisens S.A.) using Aplisens Mobile Configurator software. The software is available on Google Play under the link:

https://play.google.com/store/apps/details?id=com.aplisens.mobile.amc.



#### 10.5.2. Compatible configuration software

- Raport 2 Aplisens under control of Windows 7 or Windows 10;
- Aplisens Mobile Configurator under control of the Android system;
- every software from other companies accepting DDL and DTM libraries.

#### 10.5.3. Method of connecting communication devices

The method of connecting communication devices to the transmitter is described in chapter  $\Rightarrow$  8.1.2. Connection of transmitters with the option of using HART communication. When using remote communication, the HART modem must be connected in parallel to the 4 ... 20 mA line. A resistance of  $\geq$  240  $\Omega$  is required between the power supply and the modem connection point. Also follow the guidelines for maximum load resistance R<sub>Lmax</sub> described in section  $\Rightarrow$  8.2.3. Resistance load in power supply line. When using measuring cards with an integrated HART master, the card manufacturer's regulations must be followed.

## 11. MAINTENANCE

# 11.1. Periodic inspections

Periodic inspections shall be carried out in accordance with applicable standards. During the inspection, check the condition of electrical terminal connections (reliability of the connections) and the stability of transmitter mounting.

## 11.2. Non-periodic inspections

If the transmitter at the installation site has been exposed to mechanical damage, overvoltage or incorrect operation of the transmitter is detected, the device shall be inspected.



If there is no signal in the transmission line or its value is improper, check the supply line, connection status on terminal blocks, connectors, etc. Check if the supply voltage and load resistance are correct.

#### 11.3. Spare parts

Parts of the transmitter that may be worn or damaged and thus replaced: cover gasket and cable gland gasket.



Other parts in case of ATEX types of transmitters may be replaced only by the manufacturer or an authorized representative.

#### 11.4. Repair

Faulty or non-operational transmitter shall be provided to the manufacturer.

#### 11.5. Returns

In the following cases, the transmitter should be returned directly to the manufacturer:

- need for repair;
- need for factory calibration;
- replacement of improperly selected/shipped transmitter.



# 12. SCRAPPING, DISPOSAL



Worn or damaged devices shall be scrapped in accordance with WEEE Directive (2012/19/EU) on waste electrical and electronic equipment or returned to the manufacturer.

# 13. HISTORY OF REVISIONS

Revision No.	Document revision	Description of changes
-	01_A1_2014-11	First version of the document. Prepared by DKD.
1	01_02.B.003_2018	Documentation update. Prepared by DKD
2	01_02.C.004_2018	New certification, documentation update. Prepared by DKD.
3	01.A.001/2021.05	New version. Prepared by DBFD.